

NOTES ON GROUPS, MATH 369.101

[First we should discuss the Prep about Exercise 1 from before. To what is $(\mathbb{Z}_{16})^\times / \langle 9 \rangle$ isomorphic? How about $(\mathbb{Z}_{16})^\times / \langle 7 \rangle$]

2-DIMENSIONAL COMPLEXES

Before we introduce complexes, we need to introduce *vertices* (plural of *vertex*), *edges* and *triangular faces* which, for our purposes, will be defined as follows.

Definition 1. A **vertex (or 0-simplex)** is a point in \mathbb{R}^n for some n , $n \geq 2$. If v_0 and v_1 are two vertices, an **edge (or 1-simplex)** corresponding to v_0 and v_1 is simply the straight line segment between the points. If v_0, v_1 and v_2 are three vertices, a **triangular face (or 2-simplex)** corresponding to the three vertices is the triangular region in the plane containing v_0, v_1, v_2 which has corners at the vertices.

Remark 1: If we think of the vertices as vectors in \mathbb{R}^n , then the points on edges and triangular faces are linear combinations of the vectors. For example, say $v_0 = (1, 2)$ and $v_1 = (3, 0)$. Then the edge between v_0, v_1 is the set of all endpoints of vectors written as

$$(1) \quad t_0 v_0 + t_1 v_1, \text{ where } t_0, t_1 \geq 0 \text{ and } t_0 + t_1 = 1.$$

(For example, the midpoint of the edge would be where $t_0 = 1/2 = t_1$. Indeed, $\frac{1}{2}(1, 2) + \frac{1}{2}(3, 0) = (2, 1)$, which is the midpoint.)

Similarly, the triangular face corresponding to v_0, v_1, v_2 is the (endpoints of vectors in the) set of all linear combinations of the form

$$(2) \quad t_0 v_0 + t_1 v_1 + t_2 v_2, \text{ where } t_0, t_1, t_2 \geq 0 \text{ and } t_0 + t_1 + t_2 = 1.$$

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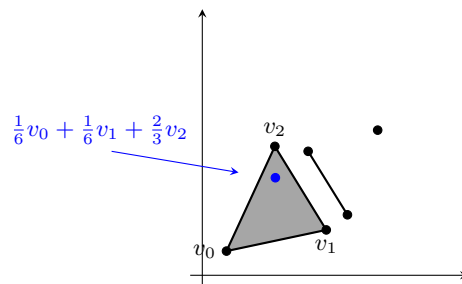


FIGURE 1. Some simplices in \mathbb{R}^2

(In the above, note that the corners correspond to $t_0 = 1; t_1 = 0; t_2 = 0$, $t_0 = 0; t_1 = 1; t_2 = 0$, $t_0 = 0; t_1 = 0; t_2 = 1$. Also note, it is not generally the case that $t_0 = t_1 = t_2 = \frac{1}{3}$ is the point that is equi-distant from the three corners (this depends on the shape of the triangular region).

Remark 2: We stopped after considering triples v_0, v_1, v_2 of vertices, and because of this Definition 1 makes sense (in most cases) for vertices in \mathbb{R}^2 (or \mathbb{R}^n , for $n \geq 2$).

The reason to specify *most cases*: What if v_0, v_1 were the same point, what does the edge between them mean? Similarly, what if v_0, v_1, v_2 were on the same line; what does the triangular face mean? We typically think of the more generic situation where Definition 1 works, but by using the linear combination description in Remark 1 we have a definition even in these degenerate cases. So, if v_0, v_1, v_2 are collinear, then the triangular face for them is the set of linear combinations in (2).

Using this linear combination description we could also continue with tuples of vertices v_0, v_1, \dots, v_k where $k \geq 3$. We would get a higher-dimensional version of the triangular face (for $k = 3$ we get a *tetrahedron*). In general, the object is called the **k -simplex** for the vertices v_0, v_1, \dots, v_k . We will stick to $k \leq 2$.

If an edge corresponds to v_i, v_j , then we say that v_i is a **border** of the edge, and v_j is also a border.

If a triangular face has corners v_i, v_j, v_k , then we say that the three edges (one for v_i, v_j , one for v_i, v_k and one for v_j, v_k) are each a **border** of this triangular face.

Definition 2. A (**simplicial**) **complex** X (with dimension ≤ 2) is a collection of vertices, a collection of edges, and a collection of triangular faces where if a simplex is in X then its borders are in X . That is,

- (1) if an edge is in X then its two borders are in X ;
- (2) if a triangular face is in X then its three borders are in X .

When we start to talk about a complex X made up of simplices, we need to make a mental division between the points in \mathbb{R}^n that make up a simplex and the simplex itself. That is, X is a collection of simplices, not a subset of \mathbb{R}^n . So a 2-simplex in X is one, indivisible, thing in X , and each of its border edges (which will be three 1-simplices) is something else on its own as an element of X .

In some of our pictures we will try to represent this separation as done in Figure 2. Despite how it is depicted, the 1-simplices (edges) in Figure 2 *come from* the same points in \mathbb{R}^2 that make up the boundary line segments of the triangle that the pictured 2-simplex *comes from*.

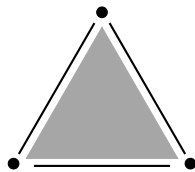


FIGURE 2. A complex consisting of one 2-simplex, its three 1-simplex borders and the three 0-simplices (corners).

1. THE CHAIN GROUP, ∂ AND HOMOLOGY

1.1. **The chain group.** Given a complex X , we can form an abelian group, the *chain group* $C_*(X)$, as follows. In fact, $C_*(X)$ will be a vector space over the field \mathbb{Z}_2 .

$C_0(X)$: Think of each vertex v_i as a vector with \mathbb{Z}_2 scalars. So there is $0v_i = 0$ and $1v_i = v_i$. We get the property that $v_i + v_i = 0$. (Despite this, $v_i \neq 0$. We are thinking of “working over \mathbb{Z}_2 ” where 2 is 0, so you cannot divide by 2.)

If $i \neq j$ then $v_i + v_j \neq 0$ is a new non-zero vector. But $(v_0 + v_1) + (v_1 + v_2) = v_0 + v_2$.

$C_1(X)$: Also think of each edge $e_{i,j}$ (the edge with borders v_i and v_j) as a vector with \mathbb{Z}_2 scalars.

$C_2(X)$: Also think of each triangular face $t_{i,j,k}$ (the triangle with borders $e_{i,j}$, $e_{i,k}$ and $e_{j,k}$) as a vector with \mathbb{Z}_2 scalars.

Exercise: If X has m vertices, how many vectors are in $C_0(X)$? (Each element is a vector $\sum_{i=0}^{m-1} c_i v_i$ where c_i is 0 or 1.)

Does the set of vertices form a basis of $C_0(X)$?

What is a basis for $C_1(X)$ and for $C_2(X)$?

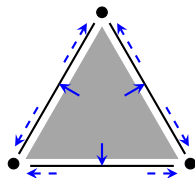
Definition 3. Define $C_*(X) = C_0(X) \oplus C_1(X) \oplus C_2(X)$.

$C_*(X)$ is a group under vector addition. The identity is 0, and the inverse of every vector is itself.

Exercise: If there are m simplices in X (0-simplices, 1-simplices and 2-simplices), then show that $C_*(X)$ is isomorphic to $\underbrace{\mathbb{Z}_2 \oplus \mathbb{Z}_2 \oplus \dots \oplus \mathbb{Z}_2}_{m \text{ times}}$

So far, the group is just encoding *formal sums* of vertices, edges and triangular faces.

Since we used \mathbb{Z}_2 for our coefficients, each element of $C_*(X)$ is just an algebraic way to record a union of vertices, edges and triangular faces in X . Note that the element $(v_0 + v_1, e_{0,1}, 0)$ is the union of v_0, v_1 and the edge between v_0, v_1 (so it is a subcomplex of X). But $(0, e_{0,1}, 0)$ is also in $C_*(X)$ and, pointedly, does not contain v_0 or v_1 , so is not a subcomplex.

FIGURE 3. A visualization of the boundary map ∂ .

1.2. **The “boundary” homomorphism ∂ .** We want to introduce a homomorphism $\partial : C_*(X) \rightarrow C_*(X)$. First, we define it on each vertex, edge or triangular face x by:

$\partial(x)$ is the sum representing the union of borders of x

(a vertex is understood to have no border, so the sum would equal zero in that case).

Now force ∂ to be a homomorphism by saying that $\partial(x+y) = \partial(x) + \partial(y)$ for any x and any y in $C_*(X)$ (think about how this is well-defined, since the set of simplices make a basis).

We can split $\partial : C_*(X) \rightarrow C_*(X)$ into dimensions by $\partial((v, e, f)) = (\partial_1(e), \partial_2(f), 0)$.

So $\partial_1 : C_1(X) \rightarrow C_0(X)$ and $\partial_2 : C_2(X) \rightarrow C_1(X)$.

Exercise: For the complex shown in Figure 4 (each simplex shown is in the complex), determine $\partial_1(e_{0,1} + e_{1,3})$, $\partial_1(e_{1,3} + e_{2,3} + e_{1,2})$ and $\partial_2(t_{0,1,2} + t_{1,3,2})$.

Exercise: If x is in $C_*(X)$, then $\partial(x)$ is the sum representing the boundary of the union of simplices represented by x .

The kernel of ∂ . Note that if $x \in C_i(X)$ for $i = 1, 2$, then $\partial(x) = 0$ means, in a certain sense, that the union of edges (if $i = 1$) or triangular faces (if $i = 2$) corresponding to x doesn't have a boundary.

Because of the border condition on the complex X , if $x = \partial_2(y)$, then x has no boundary (the boundary of a union of triangles doesn't itself have any boundary vertices – vertices that are “at an end by themselves,” and so $\partial_1(\partial_2(y)) = 0$).

Proposition 1. For any $x \in C_*(X)$, $\partial(\partial(x)) = 0$.

The image of ∂ . If $\partial_i(x) = y$ for some y then y represents a union of edges when $i = 2$ (or union of vertices when $i = 1$), that are the boundary of a union of triangular faces (or of edges).

Exercise: Show that if $y = \sum_{i=1}^m c_i v_i \in C_0(X)$ and $y = \partial_1(x)$ for some $x \in C_1(X)$, then the number of coefficients c_i that are non-zero must be even.

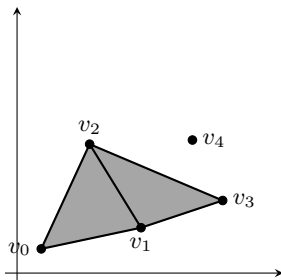


FIGURE 4. Example complex in \mathbb{R}^2

For the case $i = 1$, say that x is one sequence of edges connected by endpoints. Then $y = \partial_1(x)$ is the pair of vertices at the extremes of this sequence, and is in the image of ∂ .

Exercise: Name all the elements of $C_0(X)$ which are in the image of $\partial_1 : C_1(X) \rightarrow C_0(X)$, where X is the complex in Figure 4.

Proposition 1 means that the image of ∂ is contained in its kernel. Since ∂ is a homomorphism, $\partial(C_*(X)) \subset C_*(X)$ is a subgroup of $\ker \partial$. It is a normal subgroup since $C_*(X)$ is an abelian group.

Definition 4. We write $H_*(X)$ for the factor group $\ker \partial / \partial(C_*(X))$. For a fixed $i = 0, 1, 2$, the factor group $\ker \partial_i / \partial_{i+1}(C_{i+1}(X))$ is denoted $H_i(X)$.

Exercise: Using the complex X in Figure 4, write out the cosets in $H_0(X)$. What group is isomorphic to $H_0(X)$?

Solution: Let N_1 be equal to the normal subgroup $\partial_1(C_1(X))$.

$H_0(X)$ is defined to be $\ker \partial_0 / N_1$.

$\ker \partial_0 = C_0(X)$: $\partial((v, 0, 0)) = (0, 0, 0)$; that is, every vertex is sent to zero by ∂ , so each element in $C_0(X) \cong \mathbb{Z}_2^5$ will be in a coset in $H_0(X)$. Note that if $i \neq j$, then v_i and v_j are independent in $C_0(X)$: the only way for $c_i v_i + c_j v_j = 0$ is if $c_i = 0 = c_j$.

If $i = 1, 2, 3$, then $v_0 + v_i$ is in the $N_1 = \partial_1(C_1(X))$ since there is a union of edges connecting v_i to v_0 : e.g. $\partial_1(e_{0,1} + e_{1,3}) = v_0 + v_3$.

Since v_i is its own inverse, this means that v_0 and v_i are in the same coset (for $i = 1, 2, 3$). Note that $v_0 \notin \partial_1(C_1(X))$ (an exercise above was that the number of non-zero coefficients had to be even), so the coset $\overline{v_0} = N_1 + v_0$ is not the identity in $H_0(X)$.

Thus, for $i = 1, 2, 3$, $N_1 + v_i = \overline{v_i} = \overline{v_0}$ (not only are these now linearly dependent in $H_0(X)$, they are equal).

v_4 is not in the same coset as v_0 : in order for $v_0 + v_4$ to be in N_1 , we would need an element of $C_1(X)$ (a union of edges) so that $v_0 + v_4$ is its boundary. This doesn't happen.

So none of $\overline{v_0}, \overline{v_4}, \overline{v_0 + v_4}$ are the identity in $H_0(X)$, but they each have order 2. The coset of anything else is either equal to one of these, or to the

identity: for example,

$$\begin{aligned}\overline{v_1} + \overline{v_4} &= \overline{v_0 + v_4} \\ \overline{v_0 + v_4} + \overline{v_3} &= \overline{v_0 + v_0 + v_4} = \overline{v_4}\end{aligned}$$

So $\{\overline{v_0}, \overline{v_4}\}$ is a basis of cosets for $H_0(X)$, and $H_0(X) = \langle \overline{v_0} \rangle \oplus \langle \overline{v_4} \rangle \cong \mathbb{Z}_2 \oplus \mathbb{Z}_2$.

Exercise: For the same complex:

- (1) $e_{0,1} + e_{1,2} + e_{0,2}$ is in $\ker \partial_1$. Find a different element in $\ker \partial_1$ and convince yourself that these two elements are a basis for $\ker \partial_1$.
- (2) Let $N_2 = \partial_2(C_2(X))$. There are only two 2-simplices (triangular faces). What is their image under ∂_2 ? What is a basis for N_2 ?
- (3) What is $H_1(X)$?

Exercise: A basis of $H_0(X)$ represents the connected components of X . A basis of $H_1(X)$ represents a set of loops in X which are not “filled” by triangular faces.

Exercise (extra): Figure out $H_1(X)$ for the X in Figure 5.

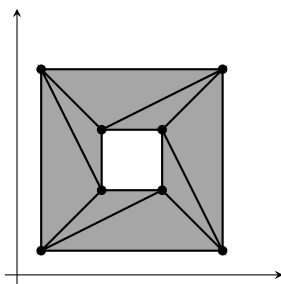


FIGURE 5. Another complex in \mathbb{R}^2